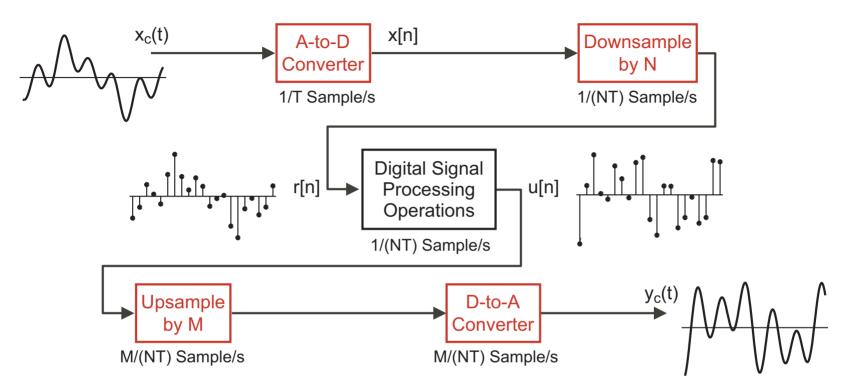
Downsampling, Upsampling, and Reconstruction

- \cdot A-to-D and its relation to sampling
- Downsampling and its relation to sampling
- Upsampling and interpolation
- D-to-A and reconstruction filtering
- Filters and their relation to convolution

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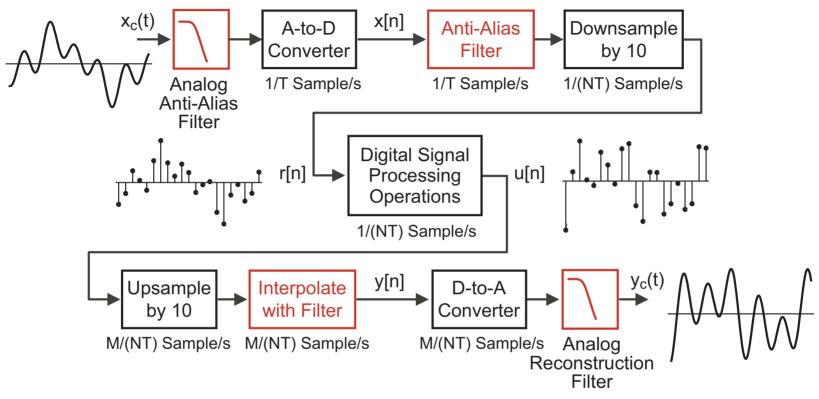
Digital Processing of Analog Signals



- Digital circuits can perform very complex processing of analog signals, but require
 - Conversion of analog signals to the digital domain
 - Conversion of digital signals to the analog domain
 - Downsampling and upsampling to match sample rates of

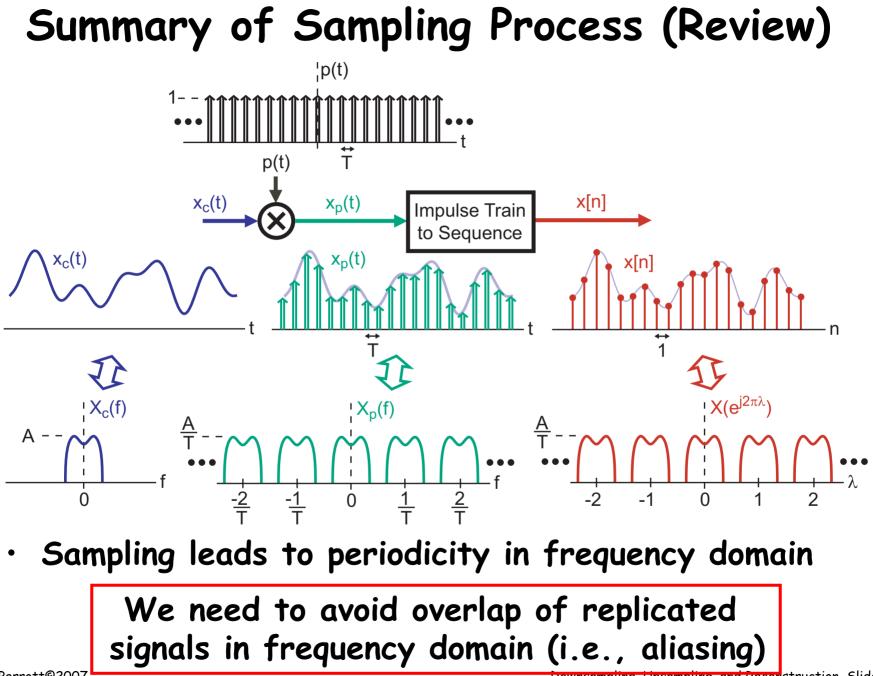
A-to-D, digital processor, and D-to-A

Inclusion of Filtering Operations

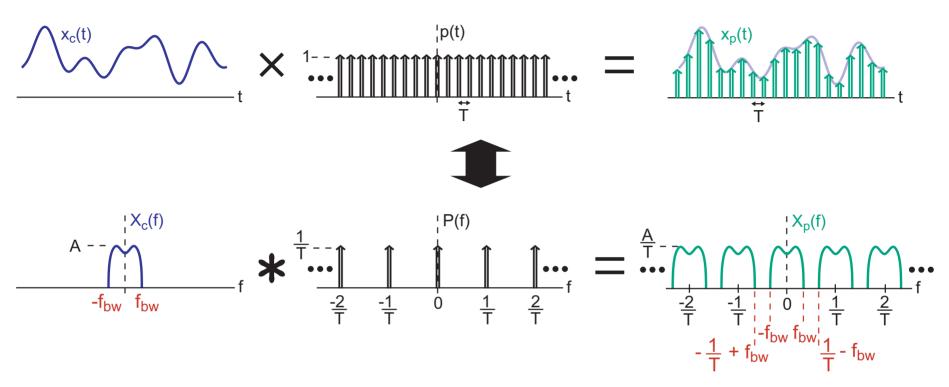


- A-to-D and downsampler require anti-alias filtering
 - Prevents aliasing
- D-to-A and upsampler require *interpolation* (i.e., *reconstruction*) filtering

- Provides `smoothly' changing waveforms M.H. Perrott@2007 Downsampl



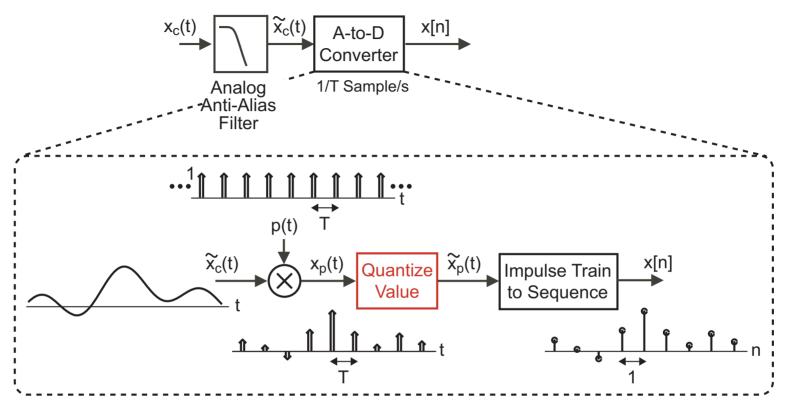
The Sampling Theorem (Review)



• Overlap in frequency domain (i.e., aliasing) is avoided if: $\frac{1}{T} - f_{bw} \ge f_{bw} \implies \boxed{\frac{1}{T} \ge 2f_{bw}}$

• We refer to the minimum 1/T that avoids aliasing as the Nyquist sampling frequency

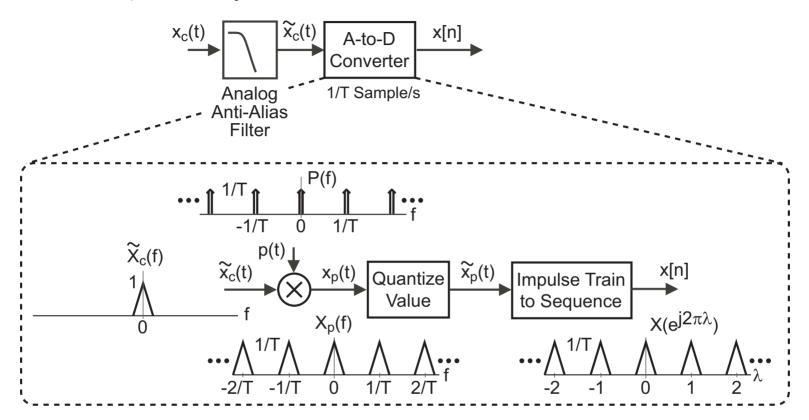
A-to-D Converter



- Operates using both a *sampler* and *quantizer*
 - Sampler converts *continuous-time* input signal into a *discrete-time* sequence
 - Quantizer converts continuous-valued signal/sequence into a discrete-valued signal/sequence
 - Introduces *quantization noise* as discussed in Lab 4

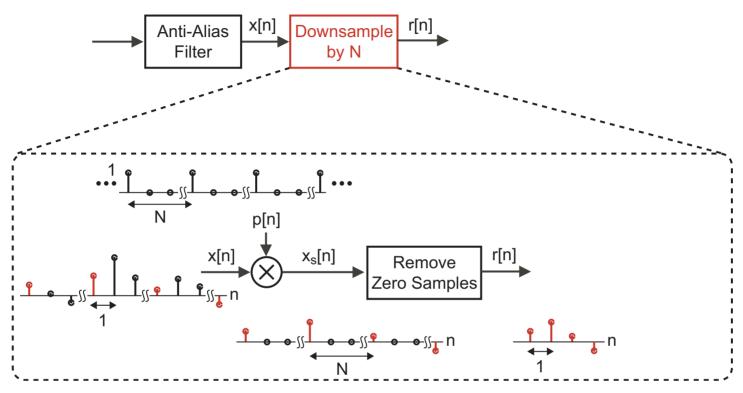
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Frequency Domain View of A-to-D



- Analysis of A-to-D same as for sampler
 - For simplicity, we will ignore the influence of quantization noise in our picture analysis
 - In lab 4, we will explore the influence of quantization noise using Matlab

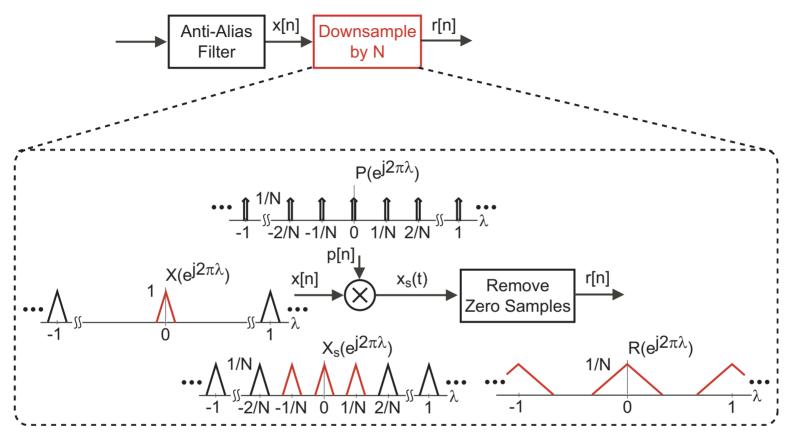
Downsampling



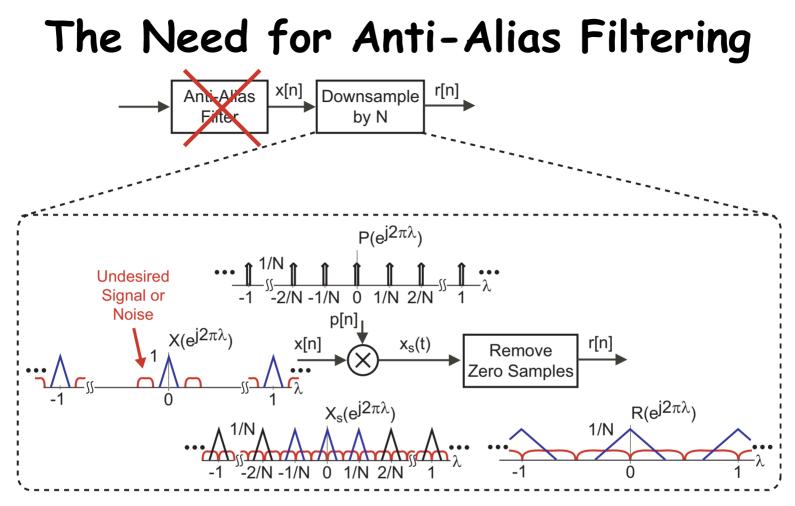
- Similar to sampling, but operates on *sequences*
- Analysis is simplified by breaking into two steps
 - *Multiply* input by impulse sequence of period N samples
 - Remove all samples of x_s[n] associated with the zerovalued samples of the impulse sequence, p[n]

• Amounts to scaling of time axis by factor 1/N M.H. Perrott©2007 • Amounts to scaling of time axis by factor 1/N

Frequency Domain View of Downsampling



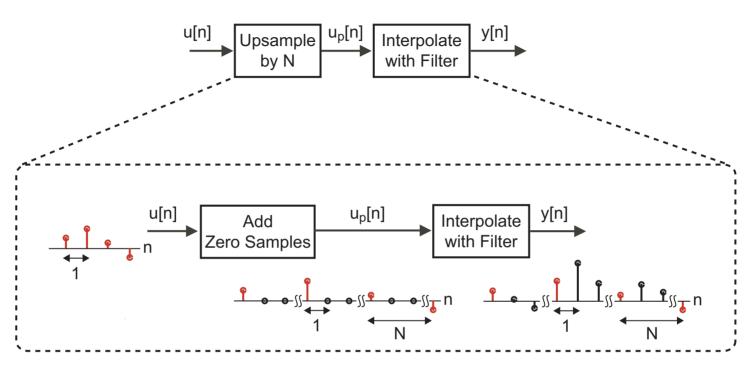
- Multiplication by impulse sequence leads to replicas of input transform every 1/N Hz in frequency
- Removal of zero samples (i.e., scaling of time axis) leads to scaling of frequency axis by factor N



 Removal of anti-alias filter would allow undesired signals or noise to alias into desired signal band

> What is the appropriate bandwidth of the anti-alias lowpass filter?

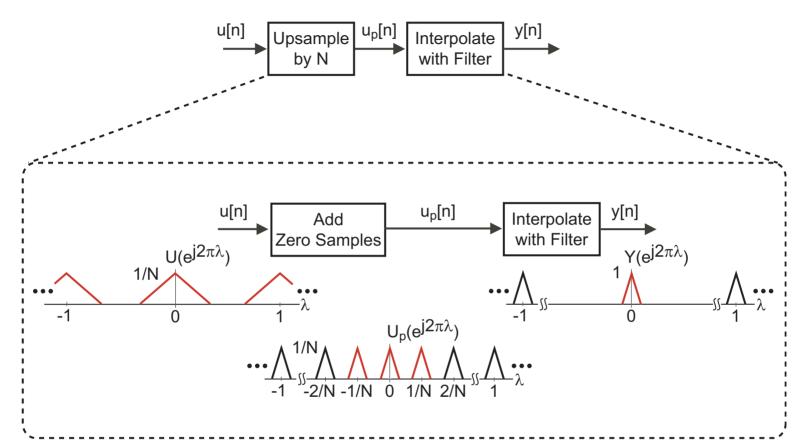
Upsampler



- Consists of two operations
 - Add N-1 zero samples between every sample of the input
 - \cdot Effectively scales time axis by factor N
 - Filter the resulting sequence, $u_p[n]$, in order to create a smoothly varying set of sequence samples
 - Proper choice of the filter leads to *interpolation* between the non-zero samples of sequence u_p[n] (discussed in Lab 5)

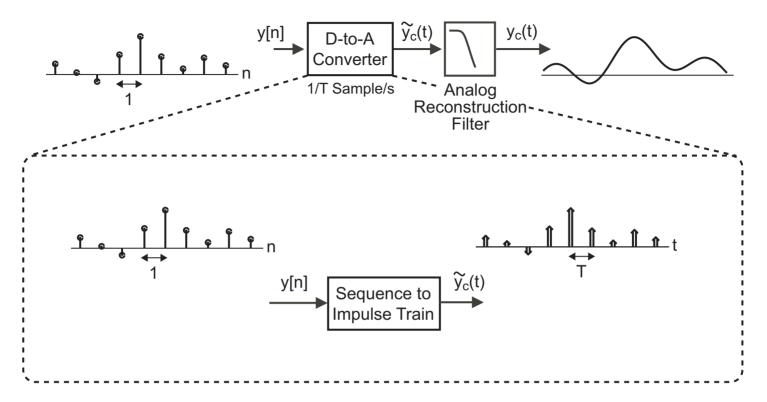
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Frequency Domain View of Upsampling

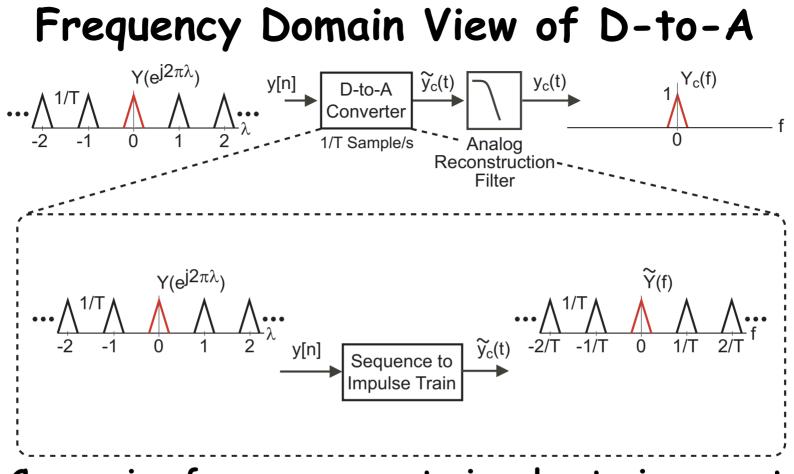


- Addition of zero samples (scaling of time axis) leads to scaling of frequency axis by factor 1/N
- Interpolation filter removes all replicas of the signal transform *except* for the baseband copy

D-to-A Converter

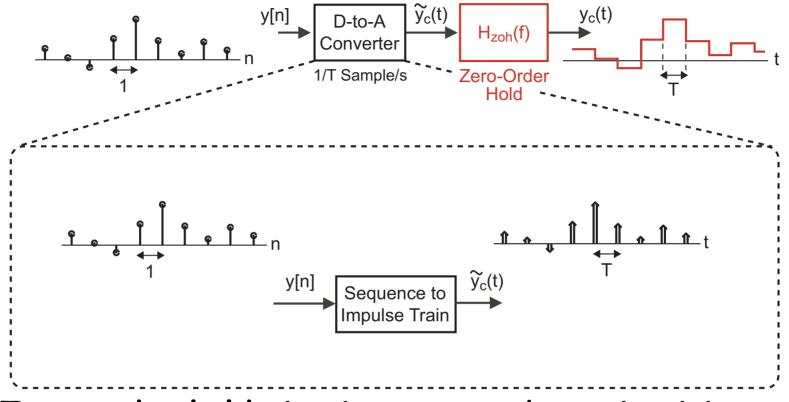


- Simple analytical model includes two operations
 - Convert input sequence samples into corresponding impulse train
 - Filter impulse train to create a smoothly varying signal
 - Proper choice of the *reconstruction filter* leads to *interpolation* between impulse train values



- Conversion from sequence to impulse train amounts to scaling the frequency axis by sample rate of D-to-A (1/T)
- Reconstruction filter removes all replicas of the signal transform *except* for the baseband copy

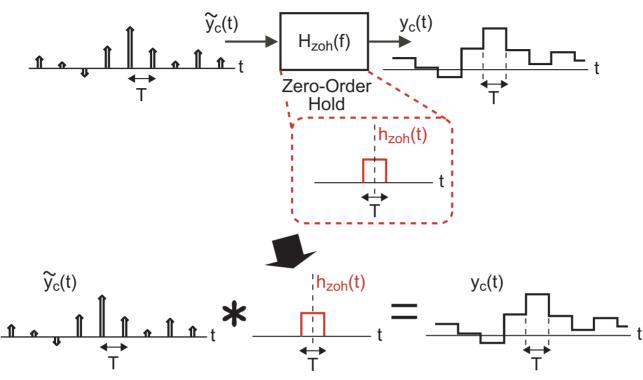
A Common Reconstruction Filter



- Zero-order hold circuit operates by maintaining the impulse value across the D-to-A sample period
 - Easy to implement in hardware

How do we analyze this?

Filtering is Convolution in Time

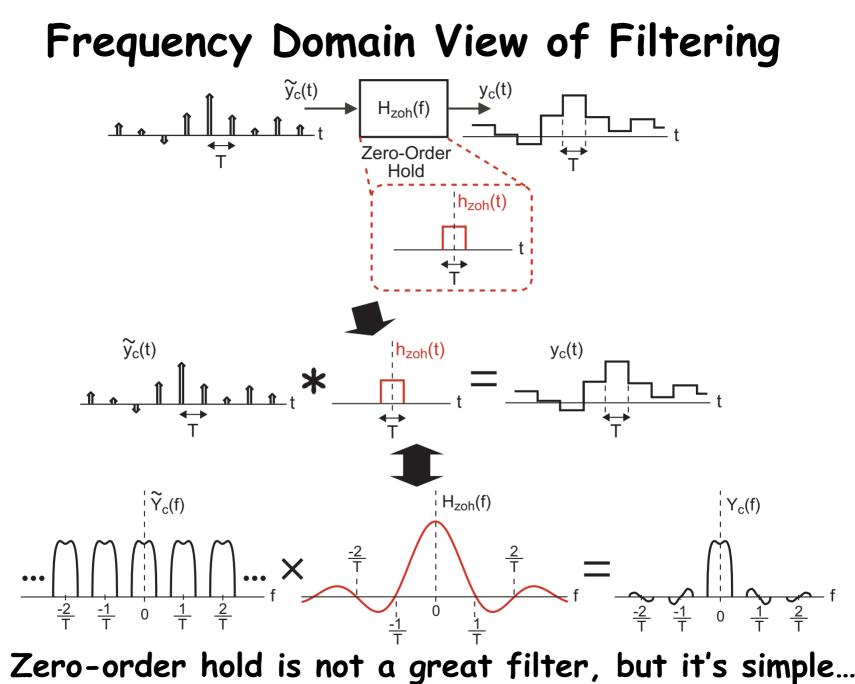


 Recall that *multiplication* in *frequency* corresponds to *convolution* in *time*

$$x(t) * y(t) \Leftrightarrow X(f)Y(f)$$

 Filtering corresponds to convolution in time between the input and the filter *impulse response*

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Downsampling, Upsampling, and Reconstruction, Slide 17

Summary

- A-to-D converters convert continuous-time signals into sequences with discrete sample values
 - Operates with the use of sampling and quantization
- D-to-A converters convert sequences with discrete sample values into continuous-time signals
 - Analyzed as conversion to impulse train followed by reconstruction filtering
 - Zero-order hold is a simple but low performance filter
- Upsampling and downsampling allow for changes in the effective sample rate of sequences
 - Allows matching of sample rates of A-to-D, D-to-A, and digital processor
 - Analysis: downsampler/upsampler similar to A-to-D/D-to-A
- Up next: digital modulation